

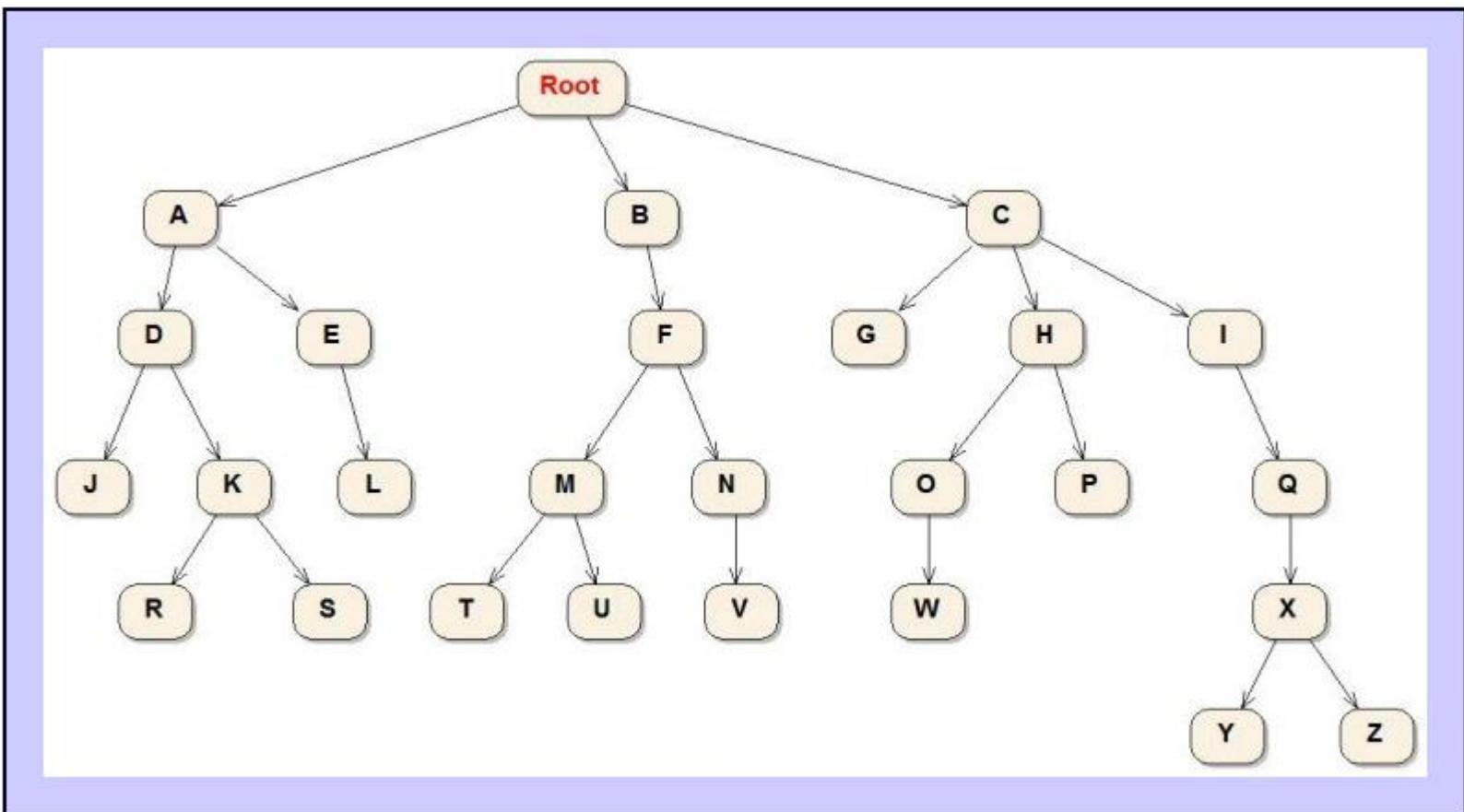
# Keynotes on Data Structure

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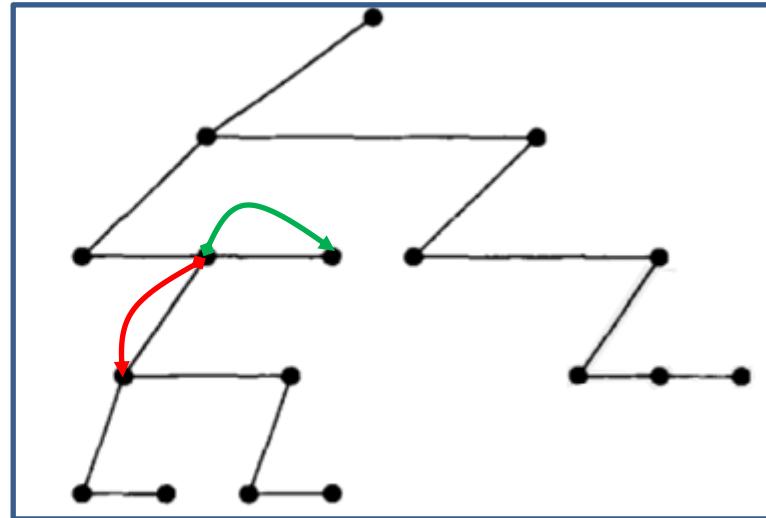
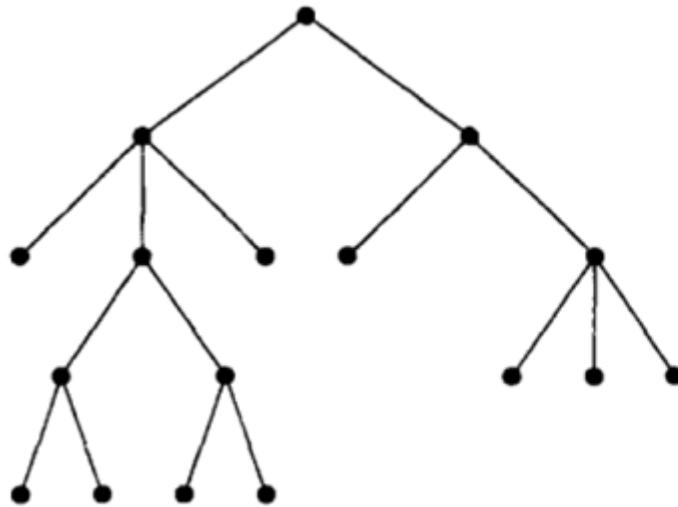
Course Code:00125401

# tree

- Populate Alphabet



# Binary representation



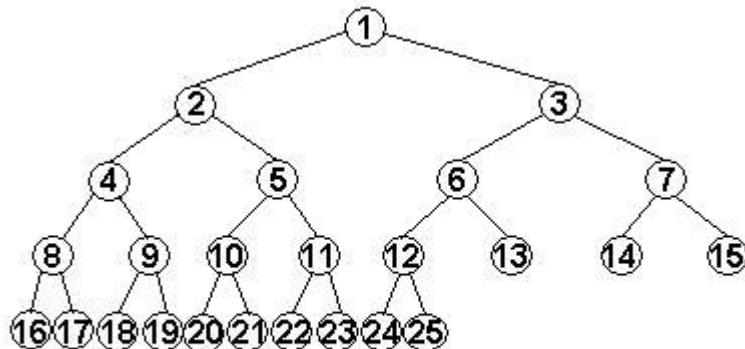
阁楼盖板变换

2pointers for each node:

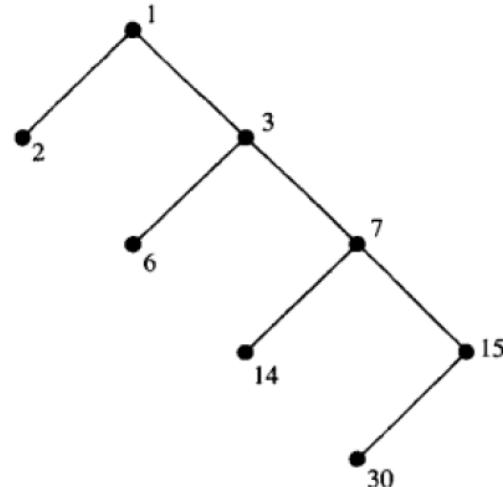
1<sup>st</sup> points to its first child;

2<sup>nd</sup> points to its sibling(if any).

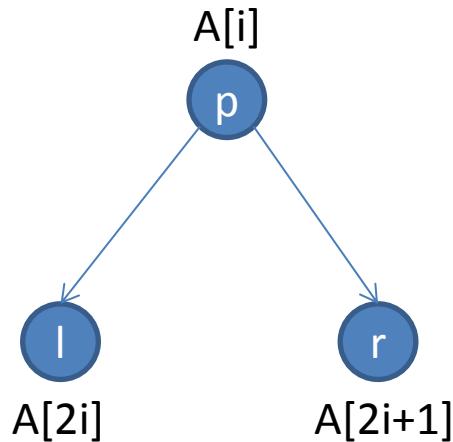
# Implicit representation



A Complete Binary Tree  
12 internal nodes, 13 terminal nodes



NEED  
NO  
POINTER!



Linear storage in an array!



# heap

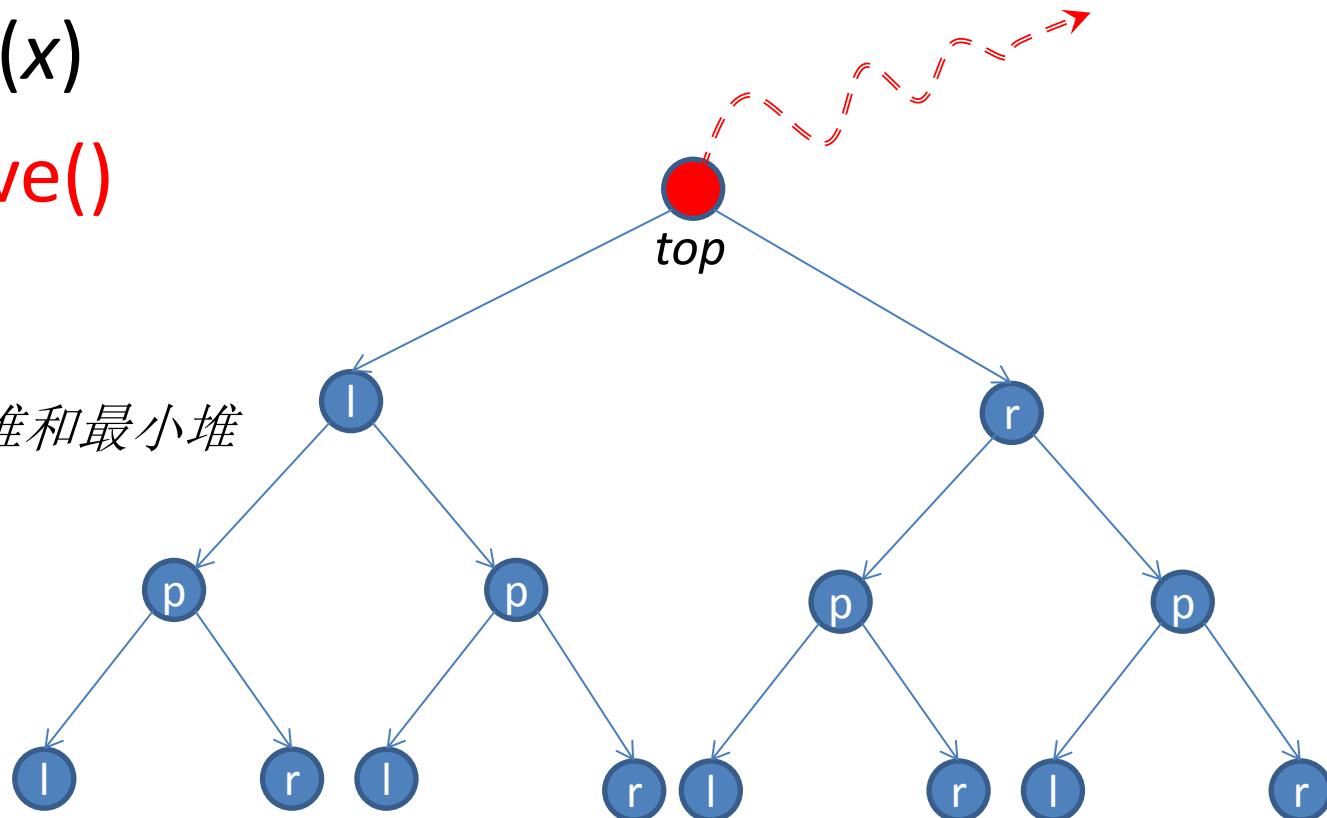
Every subtree of a heap is another heap.

- Priority-queue

- insert( $x$ )

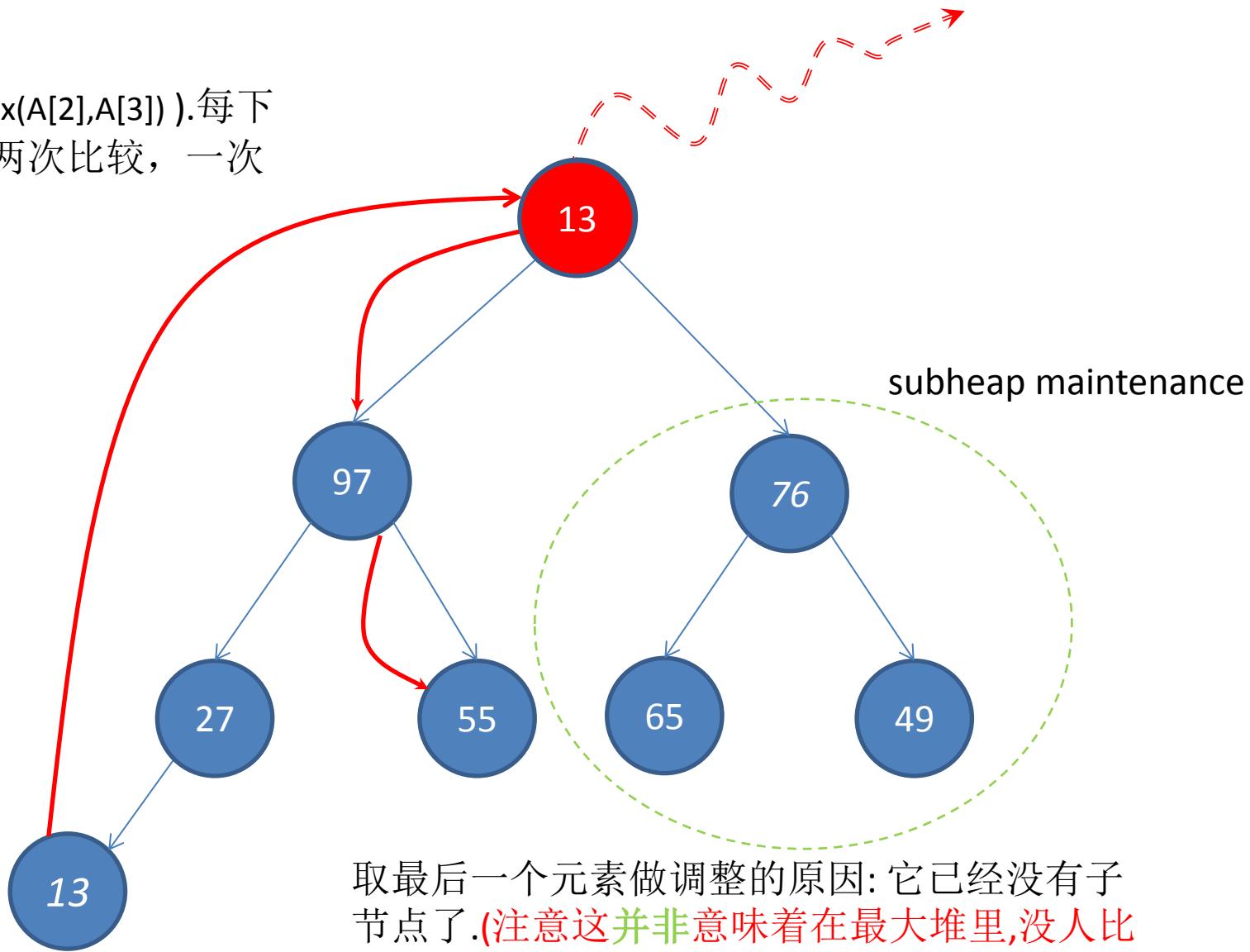
- remove()

两种：最大堆和最小堆



# Heap adjustment

$\text{Max}(A[1], \max(A[2], A[3]))$ . 每下降一层，需两次比较，一次交换



## Heap adjustment for 最大堆

算法 *Remove\_Max\_from\_Heap*( $A, n$ )

输入:  $A$  (用来表示堆的大小为  $n$  的数组)

输出: *Top\_of\_the\_Heap* (堆中最大的元素)、 $A$  (调整后的堆) 和  $n$  (调整后堆的大小; 若  $n = 0$ , 则堆为空)

**begin**

**if**  $n = 0$  **then** print "the heap is empty"

**else**

*Top\_of\_the\_Heap* :=  $A[1]$ ;

$A[1]$  :=  $A[n]$ ;

$n = n - 1$ ;

    parent := 1;

    child := 2;

**while**  $child \leq n - 1$  **do**

**if**  $A[child] < A[child + 1]$  **then**  
        **child** :=  $child + 1$ ;

**if**  $A[child] > A[parent]$  **then**  
        **swap**( $A[parent], A[child]$ );  
        parent :=  $child$ ;  
        child :=  $2 * child$ ;  
        **else**  $child := n$  {终止循环}

**end**

Max(left\_child, right\_child)

比较  $A[n]$  与 Max(left\_child, right\_child)

$2.5 \lfloor \log_2 n \rfloor$

堆排序适合较大的  $n$

图 4.7 算法 *Remove\_Max\_from\_Heap*

# insert( $x$ ) for 最大堆

算法 *Insert\_to\_Heap*( $A, n, x$ )

输入:  $A$  (用来表示堆的大小为  $n$  的数组) 以及  $x$  (某个数)

输出:  $A$  (调整后的堆) 以及  $n$  (调整后堆的大小)

**begin**

$n := n + 1$ ; {假设数组不会越界}

$A[n] := x$ ;

$child := n$ ;

$parent := n \text{ div } 2$ ;

**while**  $parent \geq 1$  **do**

**if**  $A[parent] < A[child]$  **then**

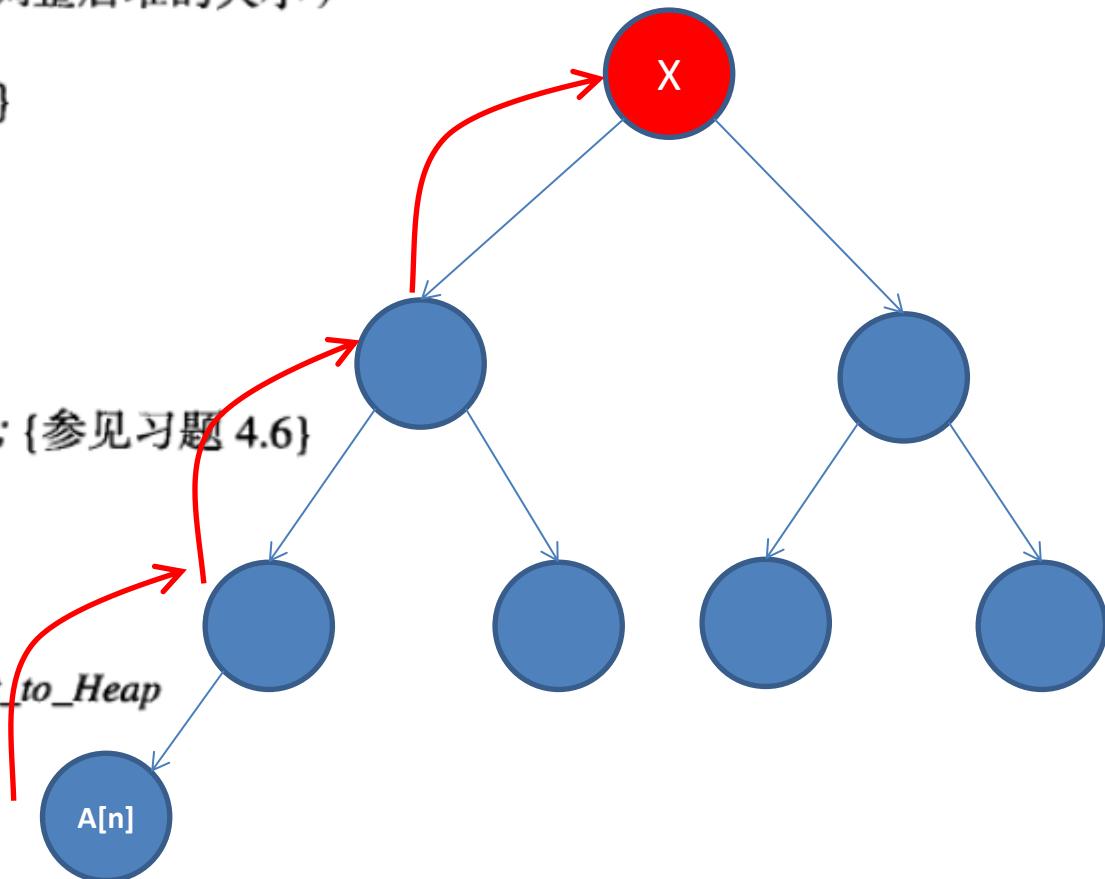
$\text{swap}(A[parent], A[child])$ ; {参见习题 4.6}

$child := parent$ ;

$parent := parent \text{ div } 2$ ;

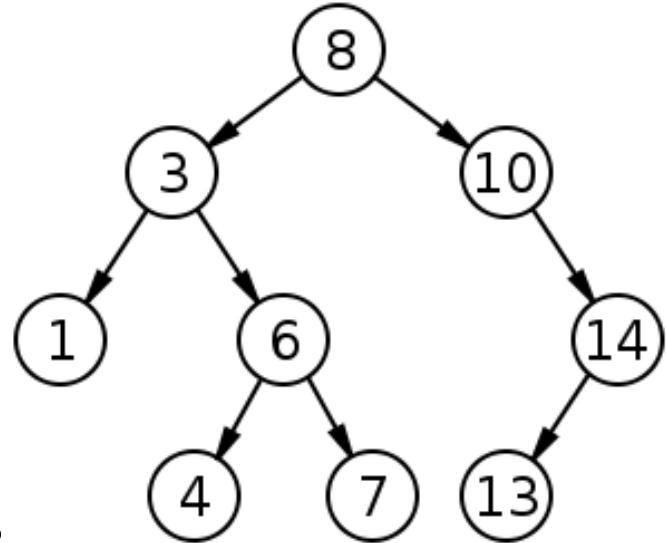
**else**  $parent := 0$  {终止循环}

图 4.8 算法 *Insert\_to\_Heap*



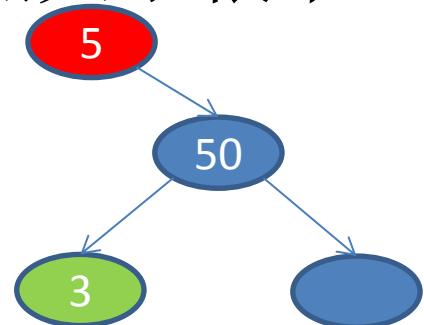
# BST: Binary Search Tree

- 左小右大.
- 右左子树都是BST树.
- 无重节点.
- 表示的是record, 存储的是key.
- 支持快速Sorting和Searching.
- Base DS for set, multisets, associative arrays



# Attention

- 原则上可以出现左子树中有一个节点大于根节点，比如：
- 或者右子树中有一个节点小于根节点
- 但是对于使用本书中的insert函数逐个插入元素生成的BST树，左(右)子树中的所有节点都小(大)于根节点



# BST search

- Simple recursive compare

**算法 *BST\_Search* (*root*, *x*)**

输入: *root* (指向二叉搜索树根节点的指针) 以及 *x* (某个数)

输出: *node* (指向含有关键字 *x* 的节点的指针, 如果上述节点  
不存在, 则指向 *nil*)

***begin***

***if* *root* = *nil* or *root*<sup>^</sup>.*key* = *x* *then* *node* := *root***

{*root*<sup>^</sup>是 *root* 的指针所指向的记录}

***else***

***if* *x* < *root*<sup>^</sup>.*key* *then* *BST\_Search*(*root*<sup>^</sup>.*left*, *x*)**

***else* *BST\_Search*(*root*<sup>^</sup>.*right*, *x*)**

***end***

图 4.9 算法 *BST\_Search*

# BST insert

- Always inserted on as **leaf** node.

算法 *BST\_Insert* (*root*, *x*)

输入: *root* (指向二叉搜索树根节点的指针) 以及 *x* (某个数)

输出: 通过插入由指针 *child* 指向的、关键字为 *x* 的节点而被改变了的树。

如果已有节点关键字为 *x*, 那么 *child* = *nil*

**begin**

**if** *root* = *nil* **then**

*create a new node pointed to by child*;

*root* := *child* ;

*root*<sup>^</sup>.*key* := *x*

**else**

*node* := *root* ;

*child* := *root* ; {初始化 *child* 使其不为 *nil* }

**while** *node* ≠ *nil* and *child* ≠ *nil* **do**

**if** *node*<sup>^</sup>.*key* = *x* **then** *child* := *nil*

**else**

*parent* := *node* ;

**if** *x* < *node*<sup>^</sup>.*key* **then** *node* := *node*<sup>^</sup>.*left*

**else** *node* := *node*<sup>^</sup>.*right* ;

**if** *child* ≠ *nil* **then**

*create a new node pointed to by child*;

*child*<sup>^</sup>.*key* := *x* ;

*child*<sup>^</sup>.*left* := *nil* ; *child*<sup>^</sup>.*right* := *nil* ;

**if** *x* < *parent*<sup>^</sup>.*key* **then** *parent*<sup>^</sup>.*left* := *child*

**else** *parent*<sup>^</sup>.*right* := *child*

**end**

Leaf's children ==nil,  
stops the while

图 4.10 · 算法 *BST\_Insert*

# Sort

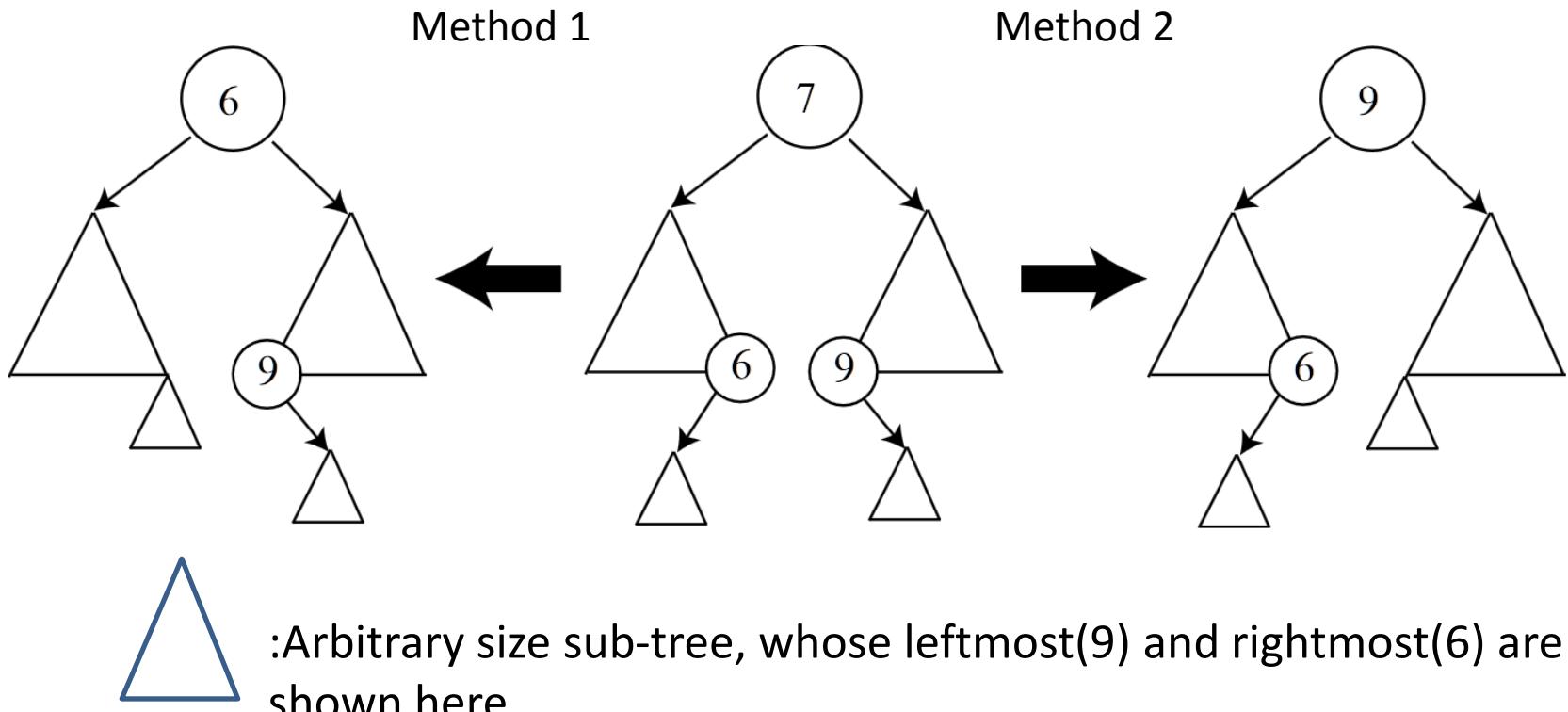
- Insertion, then traverse *in-order*

# BST delete

Say delete node \*p

- A. p has no children
  - simple deletion
- B. p has only one children
  - simple deletion and concatenation
- C. p has two children
  - two methods

# C: p has 2 children

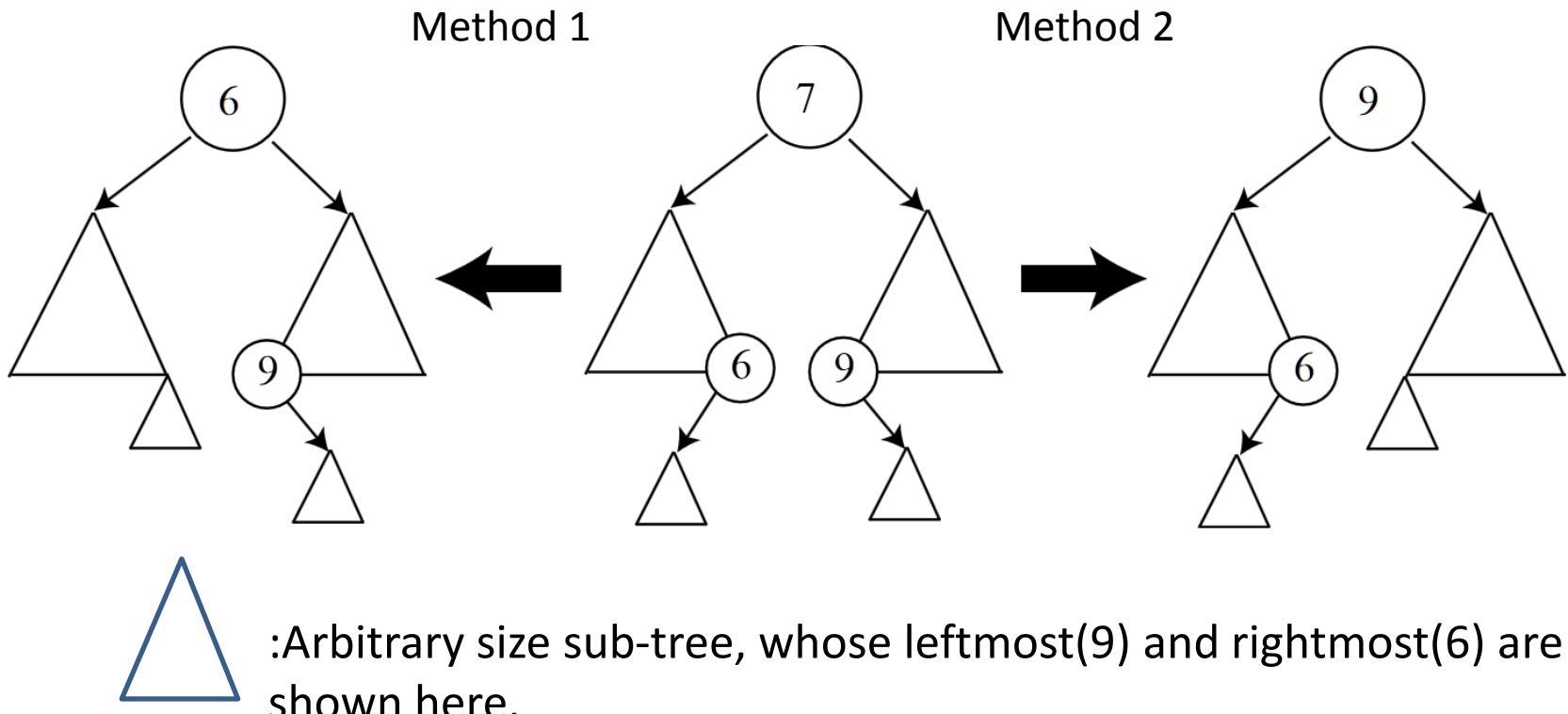


*We pop a node larger than the entire left subtree,*

*or*

*Pop a node smaller than the entire right subtree*

# C: p has 2 children



仅使用于一种删除方式将造成明显的不平衡

### 算法 *BST\_Delete* (*root*, *x*)

输入: *root* (指向二叉搜索树根节点的指针) 以及 *x* (某个数)

输出: 如果存在关键字为 *x* 的节点, 则将其删除从而改变这棵树

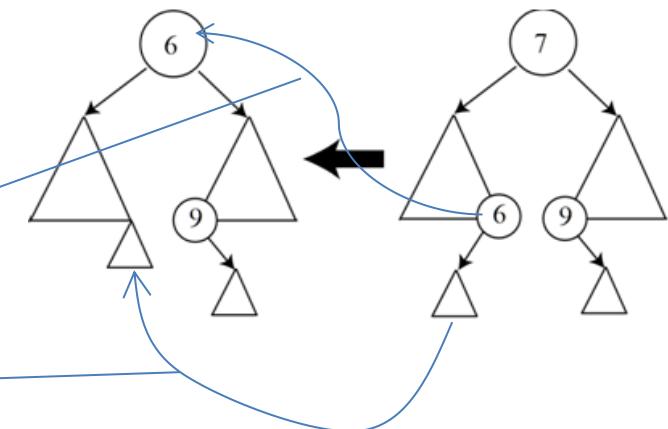
{假设永远不会删除根节点, 且任意两个节点都不相同。}

**begin**

```
node := root ;
while node ≠ nil and node^.key ≠ x do
    parent := node ;
    if x < node^.key then node := node^.left
    else node := node^.right ;
    if node = nil then print("x is not in the tree") ; halt ;
    if node ≠ root then
        if node^.left = nil then
            if x ≤ parent^.key then
                parent^.left := node^.right
            else parent^.right := node^.right
        else if node^.right = nil then
            if x ≤ parent^.key then
                parent^.left := node^.left
            else parent^.right := node^.left
        else {两个子节点的情况}
            node1 := node^.left ;
            parent1 := node ;
            while node1^.right ≠ nil do
                parent1 := node1 ;
                node1 := node1^.right ;
            {下面开始做真正的删除}
            parent1^.right := node1^.left ;
            node^.key := node1^.key
```

Method 1

找left subtree中最右  
下的节点(key最大者)



**end**

# complexity

- Search, insertion and deletion

## Time complexity in big O notation

	Average	Worst case
<b>Space</b>	$O(n)$	$O(n)$
<b>Search</b>	$O(\log n)$	$O(n)$
<b>Insert</b>	$O(\log n)$	$O(n)$
<b>Delete</b>	$O(\log n)$	$O(n)$

Depth of the tree depends on the balance of the tree.  
Induction to **self-balancing tree**

# AVL and Red-Black

- Self-balancing tree

Time complexity in big O notation		
	Average	Worst case
<b>Space</b>	$O(n)$	$O(n)$
<b>Search</b>	$O(\log n)$	$O(\log n)$
<b>Insert</b>	$O(\log n)$	$O(\log n)$
<b>Delete</b>	$O(\log n)$	$O(\log n)$